

Lesson 35 Non-homogeneous systems, Variation of Parameters

$$\underline{\text{EX:}} \begin{cases} \frac{dx_1}{dt} = x_1 \\ \frac{dx_2}{dt} = x_2 \end{cases}$$

$$\vec{x}' = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \vec{x}$$

$$(1): x_1 = c_1 e^t$$

$$(2): x_2 = c_2 e^t$$

$$\vec{x} = \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} e^t = c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^t + c_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} e^t$$

$$\det(A - rI) = (1-r)^2 = 0$$

$$r=1, 1 \leftarrow \text{double root!}$$

$$(A - (1)I) \vec{a} = \vec{0}$$

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \vec{a} = \vec{0}$$

Multiplicity of root r of
 $\det(A - rI) = 0$

is called the algebraic multiplicity
of the e-value. The dimension
of the e-space for e-val r is
called the geometric multiplicity.

All solutions called the
eigenspace for eval $r=1$.

This e-space is 2 dim^e!

$$\vec{a} = \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Get 2 solⁿs: $\begin{pmatrix} 1 \\ 0 \end{pmatrix} e^t$ and $\begin{pmatrix} 0 \\ 1 \end{pmatrix} e^t$

Fact: (geom. mult) $\leq$ (alg. mult).

What does $\det(A) = 0$ mean?

$$2 \times 2 \text{ case: } \det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc = 0$$

$$ad = bc$$

$$\frac{a}{c} = \frac{b}{d} = k$$

First row = k times the second row ... if $c, d \neq 0$.

Possibilities: $A = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$, $A = \begin{bmatrix} \text{row} & 0 \\ 0 & 0 \end{bmatrix}$, $A = \begin{bmatrix} 0 & \text{row} \\ 0 & 0 \end{bmatrix}$

or one row is a multiple of the other.

Hmmm, but $[0,0]$ is a multiple of $[c,c]$. $c=0$.

So $\det(2 \times 2) = 0$ means one row = mult of the other.

Word: Rows are linearly dependent.

Linearly independent means rows not parallel. They form a coordinate system for $\mathbb{R}^2$.

In $\mathbb{R}^n$: A is $n \times n$. $\det(A) = 0$ means rows are lin. dependent.

Defⁿ: Vectors lin. independent means:

$$\text{If } c_1 \vec{x}_1 + c_2 \vec{x}_2 + \dots + c_n \vec{x}_n = \vec{0}$$

then all the c 's must = 0.

Consequently: Vectors are lin dependent if one is a linear combo of the others.

The Wronskian connection: $\vec{x}' = A \vec{x}$, A $n \times n$.

$\vec{x} = c_1 \vec{x}_1 + \dots + c_n \vec{x}_n$ is the gen^l solⁿ exactly

when solⁿs $\vec{x}_1, \dots, \vec{x}_n$ are linearly independent.

Non-homogeneous system: $\vec{x}' = \begin{bmatrix} -3 & 1 \\ 1 & -3 \end{bmatrix} \vec{x} + \underbrace{\begin{pmatrix} 1 \\ 2 \end{pmatrix}}_{\vec{g}} e^{2t}$

$$\vec{x}' = A \vec{x} + \vec{g}$$

Step 1 = Solve homog syst: $\vec{x}' = A \vec{x}$

Get $\vec{x}_c = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-2t} + c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-4t}$ by usual method.

Step 2: Need particular solⁿ $\vec{x}_p$ to

$$\vec{x}' = A\vec{x} + \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{2t}$$

Hmmm. Try $\vec{x}_p = \vec{b} e^{2t}$ ← Safe! 2 is not an e-val

Method of undetermined coefficients: Plug it in. Make it work.

$$\vec{x}_p' = 2\vec{b}e^{2t} \stackrel{\text{want}}{=} A\vec{b}e^{2t} + \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^{2t} \leftarrow \text{divide out } e^{2t} \text{'s}$$

$$2\vec{b} = A\vec{b} + \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\begin{cases} 2b_1 = -3b_1 + b_2 + 1 \\ 2b_2 = \underbrace{b_1 - 3b_2}_{A\vec{b}} + 2 \end{cases}$$

$$(A - 2I)\vec{b} = -\begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\begin{cases} -5b_1 + b_2 = -1 \\ b_1 - 5b_2 = -2 \end{cases}$$

Cramer's rule: Get $\begin{cases} b_1 = \frac{7}{24} \\ b_2 = \frac{11}{24} \end{cases}$

$$\text{So } \vec{x}_p = \frac{1}{24} \begin{pmatrix} 7 \\ 11 \end{pmatrix} e^{2t}$$

Step 3: Gen^l solⁿ $\vec{x} = \vec{x}_c + \vec{x}_p$

↑
Gen^l solⁿ
to homog

↑
One stupid part solⁿ

$$\vec{x} = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-2t} + c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-4t} + \frac{1}{24} \begin{pmatrix} 7 \\ 11 \end{pmatrix} e^{2t}$$

Method Undet Coeff : $\vec{x}' = A \vec{x} + \vec{g}$

$\uparrow$ const coeff $\uparrow$ special form

$\vec{g}$	Try $\vec{x}_p =$
$\begin{pmatrix} 3 \\ 4 \end{pmatrix} e^{rt}$	$\vec{x}_p = \vec{b} e^{rt}$ $\leftarrow$ danger if $r = \text{e.val of } A$
$\begin{pmatrix} 3 \\ 4 \end{pmatrix} t^2$	$\vec{b}_2 t^2 + \vec{b}_1 t + \vec{b}_0$ $\leftarrow$ danger if $r=0$ is e-val
$\begin{pmatrix} 3 \\ 4 \end{pmatrix} \cos \omega t$ or $\begin{pmatrix} 5 \\ 6 \end{pmatrix} \sin \omega t$ or combo	$\vec{A} \cos \omega t + \vec{B} \sin \omega t$ $\leftarrow$ danger if $r = \pm i\omega$ is e-val
$\begin{pmatrix} 3 \\ 4 \end{pmatrix} t^5 e^{2t} \sin 3t$	You can guess it. Need 12 vectors!

When in danger, use variation of parameters.

$$\vec{x}' = A \vec{x} + \vec{g}$$

Homog solⁿ : $\vec{x} = \underline{c_1} \vec{x}_1 + \underline{c_2} \vec{x}_2$

Try $\vec{x}_p = \underline{u_1} \vec{x}_1 + \underline{u_2} \vec{x}_2$ where u 's are funs.

Need $\vec{x}_p' = A \vec{x}_p + \vec{g}$

$$u_1' \vec{x}_1 + u_2' \vec{x}_2 + \underline{u_1 \vec{x}_1'} + \underline{u_2 \vec{x}_2'} = \underbrace{A [u_1 \vec{x}_1 + u_2 \vec{x}_2]}_{\underline{u_1 A \vec{x}_1} + \underline{u_2 A \vec{x}_2}} + \vec{g}$$

$\nwarrow$ want

$$u_1' \vec{x}_1 + u_2' \vec{x}_2 = \vec{g}$$

$$\underbrace{[\vec{x}_1, \vec{x}_2]}_{\text{fund matrix}} \begin{pmatrix} u_1' \\ u_2' \end{pmatrix} = \vec{g}$$

~~X~~ = fund
matrix

$\uparrow$
 $\vec{u}'$

Var of Par:

$$\boxed{\vec{u}' = \vec{g}}$$

2x2 use Cramer's
n x n use Gaussian elim.

Solve for $\vec{u}'$. Integrate to get u_1, u_2 .

$$\text{Gen}^l \text{ Sol}^n: \quad \vec{x} = \underbrace{(c_1 \vec{x}_1 + c_2 \vec{x}_2)}_{\vec{x}_c} + \underbrace{(u_1 \vec{x}_1 + u_2 \vec{x}_2)}_{\vec{x}_p}$$

33, 34, 35 due Wed, Proj 3 due Thurs.