

$$R(\dot{I}_2 - \dot{I}_1) + \frac{1}{C} I_2 = \dot{E}(t)$$

$$L \ddot{I}_1 + R(\dot{I}_1 - \dot{I}_2) = 0$$

Remark: $\underline{E}x$: $y'' + 5y' + y^2 = \cos t$ (*)

Can turn a higher order ODE into a first order system

Trick: Let $x_1 = y(t)$
 $x_2 = y'(t)$

First eqn easy: $\frac{dx_1}{dt} = y'(t) = x_2$

$$\frac{dx_2}{dt} = y''(t) \underset{\substack{\uparrow \\ \text{from (*)}}}{=} -5y' - y^2 + \cos t = -5x_2 - x_1^2 + \cos t$$

$$\begin{cases} \frac{dx_1}{dt} = x_2 \\ \frac{dx_2}{dt} = -x_1^2 - 5x_2 + \cos t \end{cases}$$

← ode45 makes you do this in matlab

2x2 Systems: $\begin{cases} \frac{dx}{dt} = f(x, y, t) \\ \frac{dy}{dt} = g(x, y, t) \end{cases}$

$$\begin{cases} x(t_0) = x_0 \\ y(t_0) = y_0 \end{cases}$$

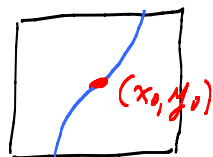
1st order 2x2 system.

↑
Initial conditions

2

E & U Thm If $f, g, \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial g}{\partial x}, \frac{\partial g}{\partial y}$ are

all continuous on a rectangle, then solⁿs to the IVP exist on a time interval about t_0 (that might be short), and solⁿ is unique.



Linear systems:

2x2

$$\begin{cases} \frac{dx_1}{dt} = a_{11}(t)x_1 + a_{12}(t)x_2 + g_1(t) \\ \frac{dx_2}{dt} = a_{21}(t)x_1 + a_{22}(t)x_2 + g_2(t) \end{cases}$$

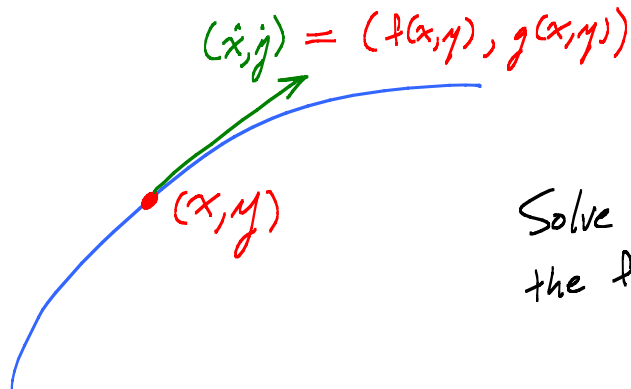
I. C. $\begin{cases} x_1(t_0) = A \\ x_2(t_0) = B \end{cases}$

E & U Thm If all the a_{ij} 's and g_j 's are continuous near t_0 , then solⁿs to the IVP exist and are unique on largest interval about t_0 where all the a 's and g 's are continuous.

Special case: Autonomous 2x2 systems =

$$\begin{cases} \frac{dx}{dt} = f(x, y) \\ \frac{dy}{dt} = g(x, y) \end{cases} \quad \leftarrow \text{no } t$$

Think $(x(t), y(t))$ curve in $\mathbb{R}^2$ in parametric form.



Solve system: Find the flow along a field.

Linear constant coeff homogeneous 1st order systems

$$\begin{cases} \frac{dx_1}{dt} = 5x_1 - x_2 & (A) \\ \frac{dx_2}{dt} = 3x_1 + x_2 & (B) \end{cases}$$

Last time: High school method: Solve (A) for x_2 .
 Plug into (B). Get 2nd order ODE in x_1 . Solve it.
 Now get x_2 from (A).

$$\text{Got } \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = c_1 \begin{pmatrix} A \\ B \end{pmatrix} e^{r_1 t} + c_2 \begin{pmatrix} C \\ D \end{pmatrix} e^{r_2 t}$$

$$\vec{x} = c_1 \vec{a}_1 e^{r_1 t} + c_2 \vec{a}_2 e^{r_2 t}$$

College method: Look for solⁿs of form $\vec{x} = \vec{a} e^{rt}$.

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} e^{rt} = \begin{pmatrix} a_1 e^{rt} \\ a_2 e^{rt} \end{pmatrix}$$

$$\vec{x} = \vec{a} e^{rt}$$

$$\begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = \begin{pmatrix} r a_1 e^{rt} \\ r a_2 e^{rt} \end{pmatrix}$$

$$\vec{x}' = r \vec{a} e^{rt}$$

Plug in and force it.

$$\begin{cases} \dot{x}_1 = 5x_1 - x_2 \\ \dot{x}_2 = 3x_1 + x_2 \end{cases}$$

$$\begin{cases} r a_1 e^{rt} = 5a_1 e^{rt} - a_2 e^{rt} \\ r a_2 e^{rt} = 3a_1 e^{rt} + a_2 e^{rt} \end{cases}$$

Cancel out e^{rt} 's

$$\begin{cases} 0 = (5-r)a_1 - a_2 \\ 0 = 3a_1 + (1-r)a_2 \end{cases}$$

$$\vec{x}' = \underbrace{\begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix}}_{A} \vec{x}$$

$$r \vec{a} e^{rt} = A \vec{a} e^{rt}$$

$$r \vec{a} = A \vec{a}$$

r eigenvalue
for
eigenvector $\vec{a}$

$$(A - rI) \vec{a} = \vec{0}$$

$$\begin{bmatrix} 5-r & -1 \\ 3 & 1-r \end{bmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Think: Cramer's rule: $a_1 = \frac{\det \begin{bmatrix} 0 & -1 \\ 0 & 1-r \end{bmatrix}}{\det \begin{bmatrix} 5-r & -1 \\ 3 & 1-r \end{bmatrix}} = 0?$

Want non-zero $\vec{a}$ solⁿs! Want Cramer's to fail!

Need

$$\det(A - rI) = 0$$

$$\det \begin{bmatrix} 5-r & -1 \\ 3 & 1-r \end{bmatrix} = (5-r)(1-r) + 3 = 0$$

$$r^2 - 6r + 8 = 0$$

$$(r-2)(r-4) = 0$$

Get two eigenvalues for A : $r = 2, 4$

Next, find e.vectors:

For $r=2$: $(A - 2I)\vec{a} = \vec{0}$

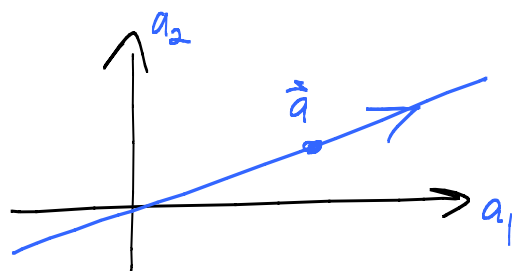
$$\begin{bmatrix} 5-2 & -1 \\ 3 & 1-2 \end{bmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \vec{0}$$

$$\left[\begin{array}{cc|c} 3 & -1 & 0 \\ 3 & -1 & 0 \end{array} \right]$$

$$\leadsto \left[\begin{array}{cc|c} 3 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right] \quad 3a_1 - a_2 = 0$$

Think: a_1 is a bound variable. a_2 is free.

Let $a_2 = t$. Then $a_1 = \frac{1}{3}a_2 = \frac{1}{3}t$



Get nice $\vec{a} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$

Just want one non-zero solⁿ.

Take $t=3$ to clear fraction.

Got $\begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{2t}$!

For $r=4$: $\left[\begin{array}{cc|c} 5-4 & -1 & 0 \\ 3 & -1-4 & 0 \end{array} \right]$

$\left[\begin{array}{cc|c} 1 & -1 & 0 \\ 3 & -3 & 0 \end{array} \right]$ $\xleftarrow{a_1 - a_2 = 0}$ 2nd eqn = 3(first)

a_1 bound. a_2 free. Let $a_2 = t$.

$a_1 = a_2 = t$ $\vec{a} = \begin{pmatrix} t \\ t \end{pmatrix} = t \begin{pmatrix} 1 \\ 1 \end{pmatrix}$. Take $t=1$.

Get $\begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{4t}$

Superposition principle holds for linear homg syst.

Get solⁿs $\vec{x} = c_1 \begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{2t} + c_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{4t}$

Is this the gen^l solⁿ? Equivalently: Can I solve any IVP with these?

Take $t=0$: $\vec{x}(0) = c_1 \begin{pmatrix} 1 \\ 3 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} A \\ B \end{pmatrix}$

$\left[\begin{array}{cc} 1 & 1 \\ 3 & 1 \end{array} \right] \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} A \\ B \end{pmatrix}$
 need $\det \neq 0$. ✓

Can get c 's for any RHS. $E \in U$ Then implies I
get the unique solⁿ!