

Lesson 6 on 7, 9 Vector Spaces (No lecture on Monday. Lessons 4, 5, 6 due Wed.)

EX: $y'' - y = 0$ $L[y] = y'' - y$. Try $L[e^{rx}] = (r^2 - 1)e^x = 0$
↑ linear trans. ↑ want $r = \pm 1$

Gen^l Solⁿ $y = c_1 e^x + c_2 e^{-x} \leftarrow \text{span}(e^x, e^{-x})$

$C^2(\mathbb{R})$ = twice cont. diff'ble fns on $\mathbb{R}$.

↑ Vector space: Box on p. 310.

Q: Are e^x, e^{-x} lin. indep.?

Suppose $c_1 e^x + c_2 e^{-x} \equiv 0 \leftarrow \text{zero vector}$

Case $c_1 \neq 0$: $c_1 e^x = -c_2 e^{-x}$

No way! $\rightarrow e^{2x} = -\frac{c_2}{c_1} \leftarrow c_1 \neq 0$

Case $c_1 = 0$: $0 \cdot e^x + c_2 e^{-x} \equiv 0$

$c_2 e^{-x} = 0$
↑ e^a is never 0

So c_2 must be zero, too.

See $c_1 = 0, c_2 = 0$. They are indep. They form a basis.

Interesting fact: $\cosh x = \frac{e^x + e^{-x}}{2}$, $\sinh x = \frac{e^x - e^{-x}}{2}$

form a basis too!

EX: $S' = \{f \in C^2(\mathbb{R}) \text{ with } f(x) \geq 0, \forall x\}$

Q: Is S' a vector space?

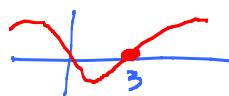
Subspace Test: Only need to check

1) closed under + ✓

2) closed under mult. by c No!

EX: $f(x) = x^2$. $c = -1$. Oops! $-x^2$ is out.

$$\underline{EX} = \{f \in C^2(\mathbb{R}) : f(3) = 0\}$$



Is a subspace of $C^2(\mathbb{R})$.

EX: M_{nm} = all $n \times m$ matrices

$$M_{22} = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

↑ ↑ ↑ ↑
basis

EX: P_n = polys of $\deg \leq n$

$$P_3 = \text{span}(1, x, x^2, x^3) \leftarrow \text{basis!}$$

Indep? $\underbrace{c_0 + c_1 x + c_2 x^2 + c_3 x^3}_{Q(x)} \equiv 0$

$$\frac{d^3 Q}{dx^3} = 3! c_3 \checkmark, \quad \frac{d^2 Q}{dx^2} = 2! c_2 \checkmark, \dots$$

Inner product space:

$$\begin{aligned} \vec{a} \cdot \vec{b} &= a_1 b_1 + \dots + a_n b_n \\ &= \vec{a}^T \vec{b} \\ &= [a_1, \dots, a_n] \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} \end{aligned}$$

Properties: Box on p. 312

$$\vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a}$$

$$(\vec{a}_1 + \vec{a}_2) \cdot \vec{b} = \vec{a}_1 \cdot \vec{b} + \vec{a}_2 \cdot \vec{b}, \quad (c\vec{a}) \cdot \vec{b} = c\vec{a} \cdot \vec{b}$$

$$\vec{a} \cdot \vec{a} \begin{cases} > 0 & \text{if } \vec{a} \neq \vec{0} \\ = 0 & \text{if } \vec{a} = \vec{0} \end{cases}$$

Norm: $\|\vec{a}\| = \sqrt{\vec{a} \cdot \vec{a}} = \sqrt{a_1^2 + \dots + a_n^2}$

$$\vec{a} \cdot \vec{b} = 0 \leftarrow \vec{a} \perp \vec{b}$$

Great thing! Orthog basis $\vec{u}_1, \dots, \vec{u}_n$

$$\vec{u}_i \cdot \vec{u}_j = 0 \text{ if } i \neq j. \quad (\vec{u}_k \neq \vec{0}, \forall k)$$

Suppose $\left(\vec{b} = c_1 \vec{u}_1 + \dots + c_n \vec{u}_n \right) \cdot \vec{u}_k$

$$\vec{u}_k \cdot \vec{b} = \underbrace{c_1 \vec{u}_1 \cdot \vec{u}_k + \dots + c_n \vec{u}_n \cdot \vec{u}_k}_{\text{all} = 0 \text{ except } c_k \vec{u}_k \cdot \vec{u}_k}$$

So $c_k = \frac{\vec{u}_k \cdot \vec{b}}{\vec{u}_k \cdot \vec{u}_k}$

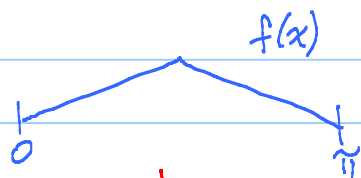
EX: $C([0, \pi]) \leftarrow$ cont. f'cus on $[0, \pi]$

$$f \cdot g = ?$$

f'cus

$$f \cdot g = (f, g) = \int_0^\pi f(x) g(x) dx$$

Johann Bernoulli



$$\text{Sin mx} \cdot \left(f(x) = \sum_{n=1}^{\infty} c_n \sin nx \right) \quad (\text{Fourier Series})$$

$$\int_0^\pi \sin nx \sin mx dx = \begin{cases} 0 & n \neq m \\ \frac{\pi}{2} & n = m. \end{cases}$$

$$\int_0^\pi f(x) \sin mx dx = c_m \underbrace{\int_0^\pi \sin^2 mx dx}_{\frac{\pi}{2}}$$

Aha!

$$c_m = \frac{2}{\pi} \int_0^\pi f(x) \sin mx dx$$

Linear Transformations: $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$

Lect 1: $T\vec{x} = A\vec{x}$

$$A = \underbrace{[T\vec{e}_1, T\vec{e}_2, \dots, T\vec{e}_n]}_{m \times n}$$

$$T \sim A$$

$$(T_1 \circ T_2)\vec{x} = T_1(T_2\vec{x})$$

$$A_1(A_2\vec{x})$$

$$= (A_1, A_2) \vec{x}$$

$\sim T_1 \circ T_2$

EX: $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ $T\vec{x} = A\vec{x}$

Inverse? Need $\text{Rank}(A) = 3$

$$\det(A) \neq 0$$

A non-singular

$$\text{Dim Row sp} = 3$$

$$\text{Dim Col sp} = 3$$

A^{-1} exists

equiv

What is T^{-1} ?

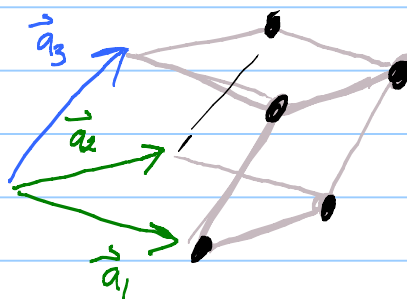
$$A\vec{x} = \vec{y} \quad \leftarrow \text{mult on left by } A^{-1}$$

$$\vec{x} = A^{-1}\vec{y}$$

Aha! $T^{-1} \sim A^{-1}$

Meaning of $\det(A)$: $A = [\vec{a}_1, \vec{a}_2, \vec{a}_3]$

$\uparrow$ 3×3



$$\det(A) = \pm \text{volume (box)}$$

$$\det(A) = 0 \quad \leftarrow \text{squashed box}$$

(could be a line)